### **EURECA:** EURopean–JapanEse Calorimeter Array

A technology demonstrator and contribution to the combined US, Japanese, and European

## Cryogenic Imaging Spectrometer onboard IXO

Piet de Korte, Dick Boersma, Marcel Bruijn, Bob Dirks, Luciano Gottardi, Roland den Hartog, Jan-Willem den Herder, Henk Hoevers, Jan van der Kuur, Bert-Joost van Leeuwen, Ad Nieuwenhuizen, Manuela Popescu, Marcel Ridder, Henk van Weers

### SRON Netherlands Institute for Space Research, Utrecht, The Netherlands

Collaborators	Institutes	GOAL	L
Jose Anquita, Fernando Briones, and Raqual Gonzalez-Arrabal Xavier Barcons, Beatriz Cobo, Francisco Carrera, Maite Ceballos, Raquel Fraga Augustin Camòn, Maria Parra Javier Sese	IMM-Instituto de Microelectronica de Madrid, Madrid Spain Instituto de Física de Cantabria, Santander, Spain I CMA, Zaragoza, Spain I CMA, Zaragoza, Spain I NA-Instituto Universitario de Investigatión en Nanociencia de Aragón, Zaragoza, Snain	• Demon astronon • Build an	onstrate technology readiness of a TES-based cryogenic instrument for future X-ray omy missions like the IXO, DIOS, XENIA, and IR-missions like SPICA. an international consortium to develop and deliver such an instrument. ECA – BASELINE
Lourdes Fabrega Reiner Rohlfs, Stephane Paltani Lorenza Ferrari, Flavio Gatti Paolo Bastia Luca Colasanti, Claudio Macculi, Luigi Piro Guido Torrioli Panu Helistö, Mikko Kiviranta Jörn Beyer, Dietmar Drung Yoshitaka Ishisaki, Takaya Ohashi Kazuhisa Mitsuda, Yoh Takei, Noriko Yamasaki Bert Monna	Institut de Ciència de Materialis de Barcelona (CSIC), Barcelona, Spain ISDC, Versoix, Villigen, Switzerland INFN and University Genua, Genua, Italy ThalesAlenia Space, Vimodrone, Italy Istituto Astrofisica Spaziale Fisica Cosmica (INAF), Rome IFN/CNR Rome, Italy VTT Sensors, Finland Physikalisch-Technische Bundesanstalt (PTB), Berlin Tokyo Metropolitan University, Tokyo, Japan Institute of Space and Astronautical Science (ISAS,YAXA), Sagamihara, Japan Systematic Design B.V., Delft, The Netherlands	<ul> <li>5 x 5 p</li> <li>2 SQUI</li> <li>base-bar</li> <li>Cryoge</li> <li>EURECC</li> <li>AE = 2</li> <li>Pixel si:</li> <li>Signal</li> <li>Electroi</li> <li>Inter-p</li> <li>Multiple</li> </ul>	p pixel array UID-amplifier read-out channels using Frequency Domain Multiplexing (FDM) and band feedback gen-free cooler based on 4K pulse tube and 50 mK dADR <b>ECA - REQUIREMENTS</b> 2 eV FWHM @ 1 keV and 5 eV @ 6 keV with high efficiency for $0.1 < E < 10$ keV size of 250 x 250 µm <sup>2</sup> al decay time < 100 µs, countrate > 500 c/s ronics dynamic range +/- 2.5 10 <sup>6</sup> $\sqrt{Hz}$ -pixel crosstalk < 5.10 <sup>3</sup> plexer suitable for 32 x 32 pixel array
Single Pixel Performance of 5 x 5 arrays	Frequency Domain Multiplexing		SQUIDS
Successful fabrication of 5 x 5 pixel arrays with Ti/AU transition-edge-thermometers and Cu/Bi (3/0.15 µm)	absorbers Signal Summing and TES-bias Topology		For now our baseline is the PTB 16-SQUID array



The science performance equals < 2 eV for E < 2 keV and 2.5 eV @ 6 keV with Cu-stem of representative heat capacity and 4 eV @ 6 keV with full mushroom (Cu/BI) absorber.



Cu-stem absorber Cu/Bi mushroom absorber

#### Single pixel AC-bias performance

Verification of the pixel read-out under FDM by comparison of pixel performance under AC- and DC-bias. Within the present error bars of the measurements the I – Vs, complex impedance, and noise characteristics are equal. Notwithstanding that the X-ray performance is still lagging behind, i.e. 3.7 eV instead of 2.5 eV. At this moment the set-up still suffers from drifts and rather low FLL-gain



Energy resolution of a pixel with Cu-stem absorber under AC-bias (370 kHz)

# FDM Frequency Range, Frequency seperation, and number of pixels/channel

The frequency range that can be used for FDM is set by: • LC capacitor size at low-frequency end, i.e. 3.5 x 3.5 mm<sup>2</sup> at 1 MHz • Voltage bias requires Q >> 170 f (MHz). Q > 4000 demonstrated • SQUID back-action noise. For  $\omega$  =  $R_{\text{TES}}$ -L<sub>SO</sub>/N.M<sup>2</sup> back action noise equals input noise. About 10 MHz for PTB-SQUID array.

So multiplexing range is: 1 < f < 10 MHz The frequency separation required for FDM is set by:

• The information bandwidth (about 10 kHz for EURECA) • Enough baseband gain-bandwidth (GBW  $\approx \Delta f$  /6) • The requirements on crosstalk between pixels (< 5.10<sup>-3</sup>)

So frequency seperation is:  $200 < \Delta f < 300$  kHz

2 

Using frequency-comb with 200 kHz channel separation 45 pixels can be read-out by one SQUID-channel.



• FDM requires that each pixel has its own LC-filter to limit the contribution of wide-band Johnson noise from neighbour pixels and to enable voltage bias. • Voltage bias requires Ohmic filterloss R<sub>ESK</sub><< R<sub>TES</sub>, and therefore LC-filters Q >>  $\omega \tau_{RISE}$ . For  $\tau_{RISE}$  = 25 µs we require Q >> 170 f (MHz) • The SQUID input inductance for current summing is the common impedance at the summing point and has to be small to circumvent summing between pixels. The current crosstalk level equals (L\_/ZL)X(f/Af). For our case L\_c < 2.8 nH (@10 MHz) for a power crosstalk in the sensor < 5.10<sup>-3</sup>. Typical SQUIDs will have an input inductance of at least 3 nH. • Ac-biasing by a comb results in predictable and correctible crosstalk levels between pixels at neighboring frequencies, which can be reduced by use of more than one bias wire pair. **Dynamic Range and Linearity** 

#### **Dynamic Range and Linearity**

• X-ray micro-calorimeters do require a large dynamic range for its electronics. For EURECA a dynamic range of +/- 2.5 10<sup>6</sup> vHz is needed. • Good SQUIDs have a typical flux noise of 0.2  $\mu_0/v$ Hz and a maximum range of +/- 0.2  $\emptyset_0$ , giving a full dynamic range of about +/- 10<sup>6</sup> vHz. (Our presently used PTB-SQUID has a 10x smaller dynamic range.) • So feedback is required to increase the SQUID dynamic range, as well as to linearize its response.

### **Baseband Feedback**

Since a feedback system has a limited gain-bandwidth product, high FLL-gains are not possible at carrier frequencies in the MHz range.
 So a base-band feedback system is required in which the gain-bandwidth of the FLL is optimized for the information bandwidth of about 10 kHz around each carrier. This can actually be done by de-modulation and re-modulation of the signal before feedback, so that the phase difference of the carriers can be compensated for.





18

### Measured (red) amplitude and phase of the error signal at the SQUID input for 8-channel baseband feedback with 35 kHZ gain-bandwidth and with model (blue)

In this system the FLL-gain at each carrier frequency will be extremely high (60 dB measured) thereby effectively nulling the carriers at the input of the SQUID. The gain-bandwidth around each carrier is set by the didtances between carriers. For a typical 200 kHz separation the gain-bandwidth equals 32 kHz, giving a FLL-gain of 3x at the signal risetime (10kHz) and about 20x at the signal decaytime (100  $\mu$ s)

#### HARDWARE FOR PTB/BESSY TEST





Measurements show that this has been successful down to the 1.8 eV energy resolution level. Up to countrates of 800 c/s more than 30% of the events have < 2 eV energy resolution.

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